





EarthCARE level 2 development projects APRIL, CLARA and DORSY final presentation

M-AOT processor and M-AOT product developed in APRIL

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M-AOT v8.x overview

- MSI stand-alone aerosol processor
- Daytime and cloud-free only
- Output resolution on native MSI grid
- Purpose: offer information on horizontal aerosol distribution complementing vertical nadir information from ATLID
- Optimal estimation based retrieval approach of aerosol optical thickness (AOT) over ocean, and where possible land, at 670 nm and over ocean at 865 nm
- Measured signal will be corrected for gaseous absorption in advance

 $T_{gas}(\lambda) = \exp(-AMF \cdot (a(\lambda) + b(\lambda) \cdot gas + c(\lambda) \cdot gas^2))$ used correction coefficients are based on line-by-line code included in MOMO (Doppler et al. 2014) applying HITRAN 2012 (Rothman et al., 2014) database

- Forward operators consist of interpolation in LUTs created with FUB in-house radiative transfer model MOMO (Hollstein and Fischer, 2012, Doppler et al. 2014)
- LUT definition / assumptions:
 25 aerosol component mixings via AOT ratios of the four basic HETEAC types (Wandinger et al. 2016)



M-AOT – LAND retrieval approach

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- Assumed signal dependence $\rho_{\lambda}(\phi_{rel}, \theta_{sun}, \theta_{sat}, \tau_{aer}, \alpha_{\lambda}, p, mix_{aer})$
- Aerosol component mixing chosen from MAC v1 (Kinne et al., 2013) climatology

Land retrieval - sensitivity

Assumptions:

- other parameters are perfectly known
- One channel at a time considered $\rho(\tau, \alpha) = \rho(\tau_0, \alpha_0) + \frac{\partial \rho}{\partial \tau} \Delta \tau + \frac{\partial \rho}{\partial \alpha} \Delta \alpha$
- Error propagation factor *E* (worst case): Assuming that $\rho(\tau, \alpha) = \rho(\tau_0, \alpha_0)$, $\Delta \rho = 0$: $\Delta \tau = -E\Delta \alpha$, $E = (\partial \rho / \partial \alpha) / (\partial \rho / \partial \tau)$



→ Assuming state: AOT = 0.2, albedo = 0.05 absolute error propagation factor of ~15 -> albedo error of 0.01 would lead to AOT error of 0.15

 \rightarrow Need for climatological albedo update that represents the current surface state reasonably well

• Optimal estimation measurement \vec{y} and state vector \vec{x} :

$$\vec{y} = \begin{pmatrix} \rho_{VIS} \\ \rho_{SWIR1} \\ \rho_{SWIR2} \end{pmatrix}, \ \vec{x} = \begin{pmatrix} \tau_{aer} \\ \alpha_{SWIR2} \\ NDVI_{SWIR} \end{pmatrix}$$

- Forward operator approach:
 - Usage of surface parameterization
 - linear interpolation in LUTs
 - inverse distance weighting of aerosol component mixing

M-AOT – LAND retrieval approach



Land retrieval – empirical surface parameterization

- MODIS BRDF/albedo climatology (provided by • Environment Canada) has been analysed and used to create a parameterization
- Estimation of VIS. SWIR-1 albedo using SWIR-2 black sky • albedo and greenness:

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 $\alpha_{\lambda} = \alpha_{SWIR2} \cdot exp(a_{\lambda SWIR2}^{NDVI_{SWIR} + b_{\lambda,SWIR2}} + c_{\lambda SWIR2}),$

where

- $a_{\lambda,SWIR2,}b_{\lambda,SWIR2,}c_{\lambda,SWIR2}$ stored in LUT
- greenness dependence via $NDVI_{SWIR} = \frac{\rho_{SWIR1} - \rho_{SWIR2}}{\rho_{SWIR1} + \rho_{SWIR2}}$
- dependent on SZA, surface biome (IGBP)



MODIS input based M-AOT LAND retrieval verification

shows reasonable agreement



0.0 0.00

0.25

0.50

AERONET AOT(675 nm)

0.75

1.00

M-AOT – OCEAN retrieval approach

- Assumed signal dependence: $\rho_{\lambda}(\phi_{rel}, \theta_{sun}, \theta_{sat}, \tau_{aer}, ws, p, mix_{aer})$
- Aerosol component mixing chosen from MAC v1 (Kinne et al., 2013) climatology
- Ocean surface is parameterized via wind speed following Cox and Munk (1954)
- Strong glint areas excluded from retrieval
- Optimal estimation measurement \vec{y} and state vector \vec{x} :

$$\vec{y} = \begin{pmatrix} \rho_{VIS} \\ \rho_{NIR} \\ \rho_{SWIR1} \\ \rho_{SWIR2} \end{pmatrix}, \ \vec{x} = \begin{pmatrix} \tau_{aer} \\ wS \end{pmatrix}$$

- currently under development: usage of aerosol component mixing based best fit in operational environment that fulfils the runtime requirement
 - development approach
 - optimal estimation of AOT for all 25 pre-defined aerosol component mixings
 - choosing the state vector for which the root-mean-squared error between forward simulated measurement and measurement is lowest

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MODIS input based M-AOT **OCEAN** retrieval verification

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MYDX A2007344 1500 006 * **M-AOT** rmse approach Official **M-AOT** default 0 50 **MODIS** product converged 0.45 0.5 0.40 380/W 25 5°W 1391 30⁴N 30°N 20.01 30°N 0 35 25.25* 25.25°N 0 30-.0 .0 AOT(band /ery good (25°I 25 ° N 20.54 20 5°N 0.25 20% 2001 15 75°N 15.75°N 0.20 0.0 MYD04 / d(2) or vi 15°N 15°N 11*8 0.0 11°N 0.15 10°N 10°N 25 5°M 13°W 0.10 01 yln 0.1 38°W 25 5°W 13°W 25.5°W 13°W 0.05 0 00 AOT (band #1) AOT (band #2) M-AOT rmse M-AOT rmse M-AOT rmse vs M-AOT rmse vs 0.6 0.6 AOT (band #1) AOT (band #2) **MODIS** operational **MODIS** operational 05 0.5 0.6 0.6 30°N 30°N **M-AOT** (] [] 0.5 (2 2 0.5 40 40 25.25°N 25.25° AOT(band rmse approach AOT(band #2) 0.4 #1) of bixel 02 30 ja 20.5°N 20.5° 0. 0. AOT(band ∌ 0.0 0. AOT(band ≉ converged 0.3 205 15.75°N 15 75°N M-AOT 10 10 11°N 0.2 11°N 0.2 0.0+ 0.0 0.1 0.2 0.4 0.6 0.2 0.4 0.6 13°W 13°W 0.1 25.5°W 25.5°W 38°W 38°W MYD04 AOT(band #1) MYD04 AOT(band #2) 0.0

Verification using M-AOT-rmse processed MODIS scenes and comparison with Maritime Aerosol Network (MAN) for 503 match-ups:

- time difference of 30 minutes
- spatial distance of 0.1°

shows reasonable agreement





ECSIM nominal test scenes

M-AOT v8.1



• Current used ecsim nominal test scenes for Halifax, Halifax aerosol, Baja and Hawaii

Halifax

- ECA_EXAA_MSI_RGR_1C_20241231T183450Z_20201125T180000Z_39316D
- ECA_EXAA_MSI_CM__2A_20241231T183452Z_**20201204**T094523Z_39316D

Halifax aerosol

- ECA_EXAA_MSI_RGR_1C_20241231T185624Z_20191029T180000Z_39316D
- ECA_EXAA_MSI_CM__2A_20241231T233450Z_**20200108**T082724Z_39316D

Baja

- ECA_EXAA_MSI_RGR_1C_20250410T213955Z_20201125T143000Z_40874D
- ECA_EXAA_MSI_CM__2A_20250410T213958Z_**20201204**T095038Z_40874D

Hawaii

- ECA_EXAA_MSI_RGR_1C_20250625T005649Z_20201026T180000Z_42043E
- ECA_EXAA_MSI_CM__2A_20250625T005649Z_**20201204**T095224Z_42043E

ECSIM based M-AOT outputs

Halifax MSI_RGR_1C v 20201125





69°W 68°W

69°W 68°W

Halifax Aerosol MSI_RGR_1C v 20191029

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ECSIM based M-AOT outputs

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Hawaii MSI RGR 1C v 20201026



Summary

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- M-AOT processor creates the M-AOT product
- aerosol optical thickness retrieval over ocean and, where possible, land that uses multi-spectral imager measurements assuming one central wavelength per VNS band
- Optimal estimation based approach used
- Usage of HETEAC based aerosol classification in M-AOT LUTs to ensure consistency between instruments
- Usage of land surface parameterization that is based on MODIS BRDF / albedo climatology
- M-AOT has been tested with ECSIM and MODIS based inputs
- Verification using true fields of ECSIM simulations and the operational MODIS product and AERONET/MAN AOTs are underway