

EarthCARE L2 validation ALGORITHM DEVELOPER NEEDS

25 May 2021 2nd EarthCARE calibration/validation workshop

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OUTLINE

- Mapping L2 products to physical quantities
- Survey of L2 processor developers' needs (respons
	- 1. Critical physical assumptions in processors
	- 2. Major retrieval uncertainties
	- 3. Validation needs
- Examples across validation paradigms: observation

- Summary of validation needs: common themes
- What can L2 algorithms provide?

Evaluation of ice microphysics assumptions using aircraft measurements

Hogan et al. (2012) used ground-based and airborne radars collocated with in-situ aircraft measurements to show that the mass-size relationship of Brown & Francis (1995) needs to be applied using the average particle diameter rather than the maximum diameter; **the latter implicitly assumes ice particles are spheres**.

- Used in-situ particle imaging measurements to characterize average ice particle shape (oblate spheroids with aspect ratio 0.6)
- Used aircraft measurements and mass-size relation to accurately model differential radar reflectivity from the Chilbolton radar
- Used in-situ PSD and mass-size relations to model radar reflectivity at X- and W-bands measured by ER-2 during the TC4 campaign
- Showed substantial reduction in an +5 dBZ over-estimate of radar reflectivity in the Rayleigh scattering regime at X- and W-bands.

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Statistical validation:

LWP used as a proxy to generate CFADs of observed and retrieved quantities in unrimed and rimed snow regimes (low vs high LWP)

Retrieved density factor

Evaluation of snow retrievals

Direct validation:

- Ground-based Doppler radar retrievals of rimed snow at Hyytiälä (BAECC 2014) are validated against in-situ estimates of snow density
	- a) Snow rate is well-correlated with $ZZV - \alpha_V N' \alpha r'$ liquid water path $\begin{bmatrix} m m h^{-1} \\ \omega \\ \end{bmatrix}$ $Z94V - \alpha_V r'$ estimated from a leight [km]
⇔ $ZZ - \alpha_v N' \text{or}$ *<u>aggregation</u>* microwave radiometer 0.1 d) Bulk particle density 600 Moisseev et al. (2017) a) refl Von Lerber et al. (2017) 400 ε $[\text{km}]$ $\overset{\circledcirc}{\cong}$ 200 **riming** $\frac{1}{2}$ 22:00 23:00 17:00 18:00 19:00 20:00 21:00 00:00 $01:00$ 02:00 03:00 -25 Time (UTC)

Mason et al. (2018), JGR-Atmospheres

Validation of rain retrievals

Direct validation:

- Maximizing correlative data:
	- EarthCARE tracks intersecting weather radar network for validating rain retrievals over oceans
	- Ground -based remote sensing: scans along EarthCARE tracks rather than vertically -pointing
- Forward -modelling independent X -band radar from ER -2 aircraft during TC4 campaign
	- Mason et al. (2017), *ACP*

Statistical validation: • joint histograms (correlations between quantities); can map precipitation regimes between observation and retrieval space

Target classification evaluation using simulated EarthCARE scenes
ATLID (A-TC):
 $\frac{1}{2}$

ATLID (A-TC):

- Detects about 25% of ice cloud by volume
- Around 5% by mass

CPR (C-TC):

- Around 50% by volume (missing cloud-tops & cirrus)
- +90% by mass (sensitive to snow)
- Up to 97% including where CPR is extinguished Synergy (AC-TC):
- ATLID provides +10% by volume not detected by CPR
- ATLID-only detections makes negligible contribution by mass of ice
- **But cloud-tops & cirrus are critical to radiation**

Target classification evaluation 12 mass fraction detected=8% Halifax Halifax **using simulated EarthCARE scenes**

ATLID (A-TC):

- Detects about 25% of liquid cloud by volume
- Around 5% by mass
- Scattered shallow liquid clouds are well-represented
- Missing 95% of liquid in deeper layers, convective cores, and collocated with rain

CPR (C-TC):

- Liquid cloud detection is very rare Synergy (AC-TC):
- Same as ATLID
- Is it possible to make a sensible assumption?
	- Assuming liquid cloud in cold rain resolves almost 80% of liquid by mass
- **Improves ACM -CAP assimilation of MSI solar radiances; downstream improvement in ACM -RT**

SUMMARY OF DEVELOPER NEEDS

- An incomplete survey of developer needs: detailed discussions in ATLID/Aerosols, CPR/Clouds and Radiation sessions
- Identified two major kinds of retrieval uncertainties:
	- Dependence on upstream target classification products: **are the features we're trying to retrieve adequately resolved?**
		- Complex & layered cloud and aerosol scenes
		- Identifying and characterizing surface types for passive and active instruments
		- Ground-based validation: "bottom-up" remote-sensed view of aerosol & cloud layers alongside insitu measurements at surface, to complement EarthCARE's blind zones
	- Universality: **how well do our physical assumptions hold in other locations/regimes?**
		- Physical assumptions may be mature, but often based on specific/limited studies
		- Opportunity to identify gaps, and target locations/regimes with campaigns
		- For statistical validation we need to be able to isolate processes: selecting/sub-setting data by location, correlated measurements, weather regime, cloud/precipitation type, etc.

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HOW CAN L2 ALGORITHMS BE LEVERAGED?

- EarthCARE L2 algorithms run with inputs from airborne and ground-based instruments
	- Benefit of validating in "retrieval space" without introducing a second retrieval
	- But requires a high level of pre-processing:
		- Calibration & correction
		- Common grid for synergistic measurements
		- Contextual information (instrument status, surface characterization, atmospheric profiles from re-analysis)
		- Description and metadata
- Can EarthCARE algorithms be used to generate validation data in "observation space"?
	- Forward-model non-EarthCARE instruments (e.g. X-band Doppler radar)
	- Forward-model EarthCARE-like instruments from ground-based configurations?

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