Calibration and Validation of EarthCARE's Cloud Profiling Radar Data Products from

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Science Driver on Next-Generation Atmos Radars – Process Study

- "... next set(s) of space measurements should focus on process studies..."
 (2010 WCRP GEWEX Workshop, 2011 Spaceborne Snowfall Measurement Workshop, 2013 Global Precip. & Cloud Meas., 2017 D-train workshop, Decadal Survey 2017, CCP)
- Capture cloud/precipitation process via
 - Multi-frequency radar data to increase measurement dynamic range & study microphysics TRMM → GPM
 - Simultaneous Doppler velocity to associate dynamics to hydrometeors CloudSat → EarthCARE
 - Capture time evolution processes
 - GEO radars (e.g. life cycle of cyclones)
 - LEO radar constellation





Forward modeling for algorithm development and validation:

High-Resolution Radar based, or Model Based



3 bands, collimated through the scanning antenna on nadir port, Ka and W also radiate at zenith

1st deployment ACE RADEX/OLYMPEX 2015

support science of GPM, CloudSat, ACE, CCP, RainCube, SWOT.

Parameters	Ku-band	Ka-band	W- band		
Frequency(GHz)	13.4	35.6	94		
Polarization	HH, HV	HH	HH		
Antenna eff. diameter	0.4 m	0.3 m			
Antenna gain	34 dBi	50 dBi			
Antenna sidelobe	-30 dB	-30 dB	-30 dB		
Antenna scan angle	±25°	±25°	±25°		
Polarization isolation	-25 dB	-	-		
Peak power	200 W	500 W	1400 W		
Bandwidth	4 MHz	4 MHz	4 MHz		
Pulsewidth	3 - 20 ms	3 - 20 ms	0.25,0.5, 1ms		
PRF (pulse rep. freq.)	5 kHz	5 kHz	5 kHz		
Vertical resolution	60 m	60 m	50, 80, 150m		
Hor.res.(@10 km alt.)	800 m	1000 m	200 m		
Ground Swath	10 km	10 km	10 km		
Sens.(@10km range)	10 dBZ	-10 dBZ	-35 dBZ		
Doppler precision	0.3 m/s	0.3 m/s	0.3 m/s		







1. Post-Launch (GPM) in the Field OLYMPEX: Olympic Mountains Experiment (Pacific NW) Nov 2015 – Jan 2016

Science Goals:

- Physical Validation of GPM
 Precipitation Algorithms (rain and snow) for GMI and DPR
- Midlatitude frontal systems and modification by complex terrain
- Merged numerical model and satellite observations
- Test hydrological applications



- Surface: Special Rain gauge networks on Quinault and Chehalis, SNOTEL, Time-Lapse Photography, Disdrometers (Parsivel, 2DVD), hot plates, Pluvios
- Radars: WSR-88D, NPOL, D3R, MMR, X and W-band from Canada, Potential Radars: C, DOW, Atmospheric River Obs, and others.
- Aircraft: DC-8 (ed: with APR-3), <u>UND Citation</u>, ER-2 (ACE/RADEX). Other potential aircrafts: Canadian NRC C580, DOE G-1 Courtesy Lynn McMurdie (UW)





OLYMPEX: GPM/ACE joint Experiment



ACE SWG & GPM GV program → 2 joint projects with multi frequency cloud-precipitation radar:

- GPM: multi-freq. radar to better constrain GPM retrievals.
- ACE: refine definition of radar for ACE mission.
- radar measurements from DC-8 & the ER-2
 = proxies to the ACE/CCP radar observables
- Ground-based radar data \rightarrow complementary view.

CRS and HIWRAP in nadir pointing configuration on ER-2



 Heymsfield, A., et al., 2017: <u>Toward Improving Ice Water Content and Snow Rate</u> <u>Retrievals from Radars Part II: Results From Three Wavelength Radar /Collocated</u> <u>In Situ Measurements and CloudSat/GPM/TRMM Radar Data</u>, *J.App.Met.Clim*.
 Chase, R. J., et al., 2018: <u>Evaluation of Triple-Frequency Radar Retrieval of</u> <u>Snowfall Properties using Coincident Airborne In-Situ Observations during</u> <u>OLYMPEX</u>, *Geophys. Res. Lett* Leinonen, J., et al., 2018: <u>Retrieval of snowflake microphysical properties from</u> <u>multi-frequency radar observations</u>. *Atmos. Meas. Tech. Discuss.*, (in review)

APR-3 on DC-8 (ESTO/AITT Program) is the first 3-frequency (Ku, Ka, W), scanning, Doppler, airborne radar.



2. ORACLES: selected NASA Earth Venture mission



ORACLES (ObseRvations of Aerosols above CLouds and their intEractionS)

- climate impacts of African Biomass Burning aerosols.
- aerosol-cloud interactions in the SE Atlantic,
 - among largest AOD on the planet.
 - largest inter-model differences in aerosol forcing assessments on the planet.
- multi-year airborne observations

COURTESY: J. REDEMANN, ARC





Composite CALIPSO lidar backscatter curtains show pervasive transport of BB aerosol transport during the first week of September 2008 as well as the underlying cloud tops.



ORACLES instruments and coordinates



In JAXA EarthCARE GV Science Team

Each IOP is 4 weeks in the

COURTESY: J. REDEMANN, ARC



The ORACLES operation



Low-altitude (~60 m) & slow legs (P3 had in situ probes)





The ORACLES APR-3 data







3. Other existing APR-2 (Ku,Ka) datasets



GPM Cold-Season Precipitation Experiment

Jan.-Feb. 2012 Toronto, ON

PI: G. Skofronick-Jackson (NASA/GSFC)



With in situ (UND Citation)

Triple co-location (APR2, UNDC, D3R) Sy et al. 2018 (revision)



2017

PI R. Kakar





3. Other existing APR-2 (Ku,Ka) datasets



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2017

PI: R. Kakar





- > ORACLES 2018 (Sept-Oct 2018)
- CAMP²Ex: Cloud & Aerosol Monsoonal Processes: Philippines Experiment (Aug-Oct 2019) PI J. Reid

Science Questions:

- To what extent are aerosol particles responsible for modulating warm and mixed phase precipitation in tropical environments?
- To what extent do aerosol induced changes in clouds and precipitation feedback into aerosol lifecycle?
- How does the **aerosol and cloud influence on** radiation co-vary and interact?
- How does land use change affect cloud and precipitation change?

NASA P-3B



Priority Measurements:

- Aerosol in-situ microphysics
- Cloud in-situ microphysics
- Cloud/precip remote sensing
- Trace Gases
- Aerosol and wind profiles (lidar)
- Radiation: Solar and IR
- State variables (P,T,U)



Courtesy F. Seidel (NASA)



B. RainCube (PI Eva Peral)

2016-2018

1 m Ka ^(*)

offset reflector

2013 **6U Concept** miniKaAR + KaRPDA 0.5 m



2015 **PECAN** Airborne Demo of miniKaAR



2016-2018 RainCube 6U Launched to ISS May'18 Deployment NET Jun'18







Summary Table **Ka-band** ESTO InVEST and ACT programs

	6U	12 U	50 kg		
Antenna size [m]	0.5	1.0	2.0		
Sensitivity [dBZ]	15	5-10	0-5		
Hor Resolution [km]	8	4	2		
Range Res [m]	250				
Beams	1	1-3	1-5		
RF Power [W]	10	10-20	10-40		

* Pre-Decisional Information – For Planning and Discussion Purposes Only



RainCube: Science motivation



Z.S. Haddad, O.O. Sy, S. Hristova-Veleva, G.L. Stephens, "Derived Observations From Frequently Sampled Microwave Measurements of Precipitation- Part I: Relations to Atmospheric Thermodynamics", *IEEE TGRS*, vol. 55 (6), 2017

Sy, O.O., Z.S. Haddad, G.L. Stephens, S. Hristova-Veleva, "Derived Observations From Frequently Sampled Microwave Measurements of Precipitation. Part II: Sensitivity to Atmospheric Variables and Instrument Parameters", IEEE TGRS, vol. 55 (5), 2017

C. Multi-Application SmallSat Tri-band Radar (MASTR)

Pre-Decisional Information -- For Planning and Discussion Purposes Only





Forward modeling for algorithm development and validation:

High-Resolution Radar based, or Model Based

Q2: how often will they approach the intersect point within minutes? Q3: how will the longitude change?

NASA

n - SPs	Δθ	AT	ХТ	Simult	DAYS	LON	Orbit simulation by R.J. Boain (JPL)					
0	DEG	KM	KM	sec	0.0	0.0	• once per day EC & CS tracks intersect within 1 minutes of each other					
29	-3.5	-393.6	107.8	112 7	1.0	177 9	\sim once per day LC & CS tracks intersect within 4 minutes of each other intersection maintenance 400° (1.45°) in langitude frame data to data					
60	5.1	567.5	155.3	162.5	2.0	14.9	• Intersection point will jump ~ 180° (±15°) in longitude from day to day.					
89	1.6	173.9	47.6	49.8	3.0	199.2	In approximately 1 month the opportunities will be spread more or less					
118	-2.0	-219.8	60.2	62.9	3.9	23.5	uniformly across longitudes.					
147	-5.5	-613.4	167.8	175.7	4.9	207.8	• For each opportunity a stretch of about 15 km will be within 2 km of each					
178	3.1	347.7	95.2	99.6	5.9	44.8	ather ground trocks					
207	-0.4	-45.9	12.6	13.1	6.9	229.1	other ground tracks.					
236	-3.9	-439.5	120.3	125.9	7.8	53.4	 In this example period of 32 days there will be 4 opportunities within 15 					
267	4.7	521.6	142.8	149.4	8.9	250.4	seconds, 6 between 15 and 60 seconds, and the rest more than 60 seconds.					
296	1.1	128.0	35.1	36.7	9.8	74.7						
325	-2.4	-265.7	72.8	76.1	10.8	259.0						
354	-5.9	-659.3	180.3	188.8	11.7	83.3						
385	2.7	301.8	82.7	86.5	12.8	280.3						
414	-0.8	-91.8	122.0	26.3	13.7	104.6						
443	-4.4	-485.4	120.2	126.2	14.7	125.0	30					
503	4.3	82.1	22.5	23.5	16.7	310.2						
532	-2.8	-311.5	85.3	89.2	17.6	134.5						
563	5.8	649.6	177.7	186.1	18.7	331.5	overpass around 12S:					
592	2.3	256.0	70.1	73.3	19.6	155.8						
621	-1.2	-137.7	37.7	39.4	20.6	340.1						
650	-4.8	-531.3	145.4	152.2	21.6	164.4	Seconds					
681	3.9	429.8	117.7	123.1	22.6	1.4						
710	0.3	36.2	9.9	10.4	23.6	185.7						
739	-3.2	-357.4	97.9	102.4	24.5	10.0						
770	-5.4	-603.7	165.2	172.9	25.5	207.0						
799	-1.9	-210.1	57.6	60.2	26.5	31.3	Low cloud Detection areas					
828	1.6	183.6	50.3	52.6	27.5	215.6						
859	-7.0	-777.6	212.6	222.7	28.5	52.6						
888	-3.4	-383.9	105.1	110.0	29.5	236.9						
917	0.1	9.7	2.7	2.8	30.4	61.2						
946	3.6	403.3	110.4	115.5	31.4	245.5	$-50\mathbf{u} - 150 - 150 - 120 - 40 - 60 - 80 - 30 - 60 - 30 - 3$					
977	-5.0	-557.8	152.7	159.8	32.4	82.5						

- Clear air surface return: data calibration, gas attenuation correction
- Marine SCu and shallow cloud detection: EC is expected to improve wrt CS, widespread regions of frequent occurrence lay along the 12-13S latitude.
- Deep convection, impact of Multiple-Scattering and depth of valid Doppler measurements: the best area is in the warm pool just north of Darwin
- Cirrus detection and profiling: almost ubiquitous.
- Almost everything else (small isolated convection) should probably not be targeted for direct comparisons due to low probability of co-location (time & space)

- Brightness Temperature product: CloudSat's Tb derived from noise floor, calibration vs AMSR-E (accuracy ~2 K, precision ~ 0.5 to 8 K depending on scene). collocated Tb reduces ambiguities of radar-only retrievals.
 - Similar product expected for EC CPR with calibration on CloudSat or GCOM-W



Forward modeling:

- High-resolution radar based
- Model based

A. NEOS³: NASA Earth Observing Systems Simulator Suite



a service-based tool suite providing simulated measurements for a wide range of instruments aimed at remote sensing of the atmosphere, on missions such as EarthCARE, ACE, GPM, A-Train, Nexrad in Space, and others, based on input from atmospheric models.

Allows user to

- select simulated storm,
- specify instrument(s) and orbit,
- specify calculation modules and produces expected measurements



This tool is developed and available. It needs a

user base for beta testing, customization, and

improvements.

- Algorithm: ➤ Input: *Airborne measurement from NICT SPIDER radar* (W-Band)
 - Output: Simulated EarthCARE Doppler products (Z,V)



Sy, O.O.; Tanelli, S.; Takahashi, N.; Ohno, Y.; Horie, H.; Kollias, "Simulation of EarthCARE Spaceborne Doppler Radar Products using Ground-Based and Airborne Data: Effects of Aliasing and Non-uniform Beam-Filling", IEEE TGRS, vol.52, no.2, 2014 EarthCARE Doppler velocity: temporal decorrelation

<u>Standard approach</u>: increase along-track integration length
 from 500 m (level 40)

from 500 m (level 1B) to N_{INT} * 500 m along-track sampling

- ✓ $V_{EC}(N_{INT} 0.5 \text{ km}) V_{TRUE}(N_{INT} 0.5 \text{ km})$ variance / N_{INT} (noisiness) if N_{INT} (I,Q) bursts are independent (theoretical performance)
- $\circ V_{EC}(N_{INT} * 0.5 \text{ km}) V_{TRUE}(0.5 \text{ km}) \text{ not always error variance reduction (when N_{INT} too large)}$
- \circ Coarser sampling \rightarrow Problem for retrieval of fine-scale features



Matched-filter approach



General statistics of EC-CPR simulations

	SPIDER-based			WACR-based			-	
		PRF = 6.1 kHz	PRF = 7 kHz	PRF = 7.5 kHz	PRF = 6.1 kHz	PRF = 7 kHz	PRF = 7.5 kHz	
	V _{EC} (0.5 km)	1.58	1.18	1.02	1.45	1.04	0.90	$\langle \rangle$
RMSE [m/s]	V _{EC} (1 km)	1.07	0.76	0.63	0.99	0.71	0.60	\sim
after integration	V _{EC} (5 km)	0.78	0.71	0.70	0.61	0.53	0.52	\mathbf{r}
	V _{EC} (10 km)	0.84	0.82	0.82	0.61	0.56	0.57	n I
BMSE [m/s]	EVM filtered	0.53	0.42	0.38	0.35	0.29	0.27	
vs V _{TRUE} (0.5 km)	REM filtered	1.15	0.65	0.53	0.94	0.46	0.36	
<u>after filtering</u>	RVA filtered	0.59	0.49	0.47	0.39	0.35	0.35	

Conclusions

- Noisiness of EarthCARE Doppler velocity estimate can be reduced without giving up the along-track sampling of data
- Proposed matched filters are applicable in practice
- Bottom-line accuracy could be improved by improving preliminary NUBF corrections (requires finer along-track sampling than 500 m)

Sy, O.O.; Tanelli, S.; Kollias, P.; Ohno, Y., 2014, "<u>Application of Matched Statistical Filters for EarthCARE Cloud Doppler Products</u>", IEEE TGRS, vol.52, no.11, pp.7297,7316, Nov. 2014



Thank you!

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APR3 data sets

- GCPEX: <u>https://ghrc.nsstc.nasa.gov/home/field-campaigns/gcpex</u>
- OLYMPEX: <u>https://ghrc.nsstc.nasa.gov/home/field-campaigns/olympex</u>
- ORACLES: <u>https://espoarchive.nasa.gov/archive/browse/oracles</u>